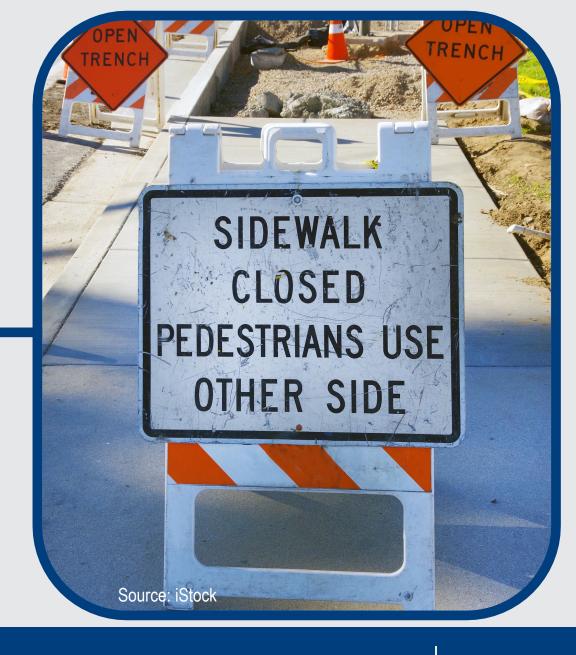
Paving the Way: Innovative Data Collection Methods for Sidewalk (or Pedestrian) Infrastructure

ITS4US Deployment Program Webinar October 24, 2024





## Webinar Agenda

#### **Purpose of this Webinar**

• This session will explore innovative methods for collecting and digitizing sidewalk data, aimed at enhancing pedestrian safety, mobility and access.

#### Agenda

- ITS4US Program Overview (Elina Zlotchenko)
- Safe Trips in a Connected Transportation Network (ST-CTN) (Randy Guensler)
- Transportation Data Equity Initiative (Anat Caspi)
- Moderated Question and Answer with the Speakers

#### Webinar Protocol

- You are encouraged to ask questions via Q&A chatbox. Questions will be added to the queue by moderators. No need to re-submit if you haven't seen it.
- The webinar recording and the presentation material will be posted on the ITS4US website within the next 2 weeks.

# Elina Zlotchenko

Program Manager, ITS4US

U.S. Department of Transportation

Intelligent Transportation Systems (ITS) Joint Program Office (JPO)





## **ITS4US Program Overview**

- A USDOT Multimodal Deployment effort, led by ITS JPO and supported by OST, FHWA and FTA
- Supports multiple large-scale replicable deployments to address the challenges of planning and executing all segments of a complete trip



**Vision:** Innovative and integrated complete trip deployments to support seamless travel for all users across all modes, regardless of location, income, or disability



## **ITS4US Deployment Program**





Heart of Iowa Regional Transit Agency (HIRTA) – Dallas County, IA

Integrated health appointment and mobility service system



Georgia Department of Transportation (GDOT) – Gwinnett County, GA

Safe trips in a connected transportation network



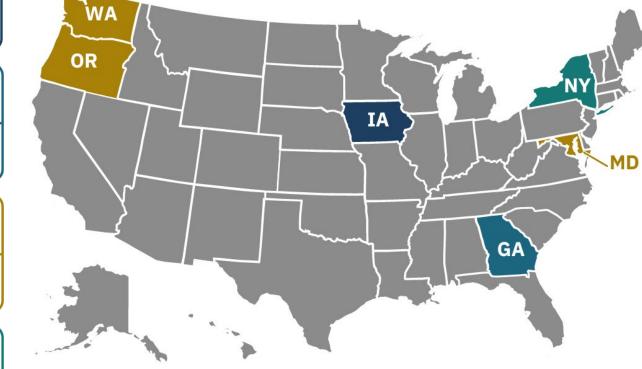
#### University of Washington (UW) – OR, WA, MD

Data and software promoting equitable travel opportunities



#### Niagara Frontier Transportation Authority (NFTA) – Buffalo, NY

Personalized, multi-modal trip planning, on-demand transportation and wayfinding



Source: USDOT



# Randall Guensler, PhD

ITS4US ST-CTN Pedestrian Impedance Lead Associate Director, NCST

Professor, School of Civil and Environmental Engineering at Georgia Institute of Technology





## Safe Trips in a Connected Transportation Network (ST-CTN)

- Gwinnett County, GA
- Key Technologies:
  - Connected Vehicle Messaging
  - Transit Signal Priority
  - Machine Learning
  - Predictive Analytics
  - Mobile Application (G-MAP)





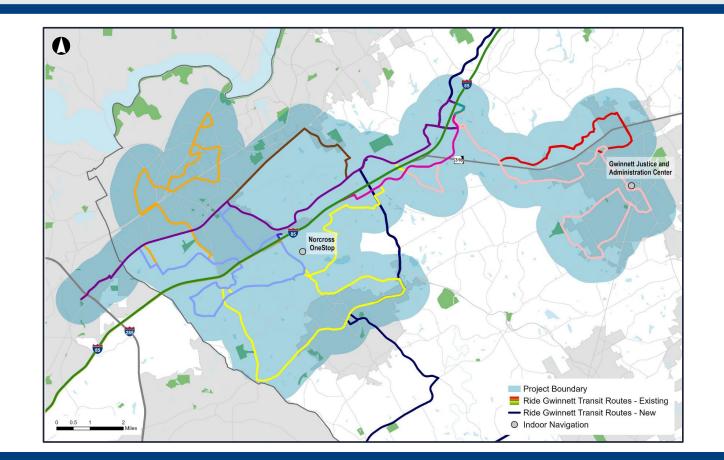
## **Deployment Concept - Goals**

- **Goal 1:** Enhance multimodal complete trip experience with the ST-CTN system functions and features, particularly for underserved communities.
- **Goal 2:** Enhance safety for ST-CTN system users, particularly for underserved communities.
- Goal 3: Improve reliability for system users, particularly for underserved communities.
- **Goal 4:** Improve mobility and accessibility for system users, particularly for underserved communities.



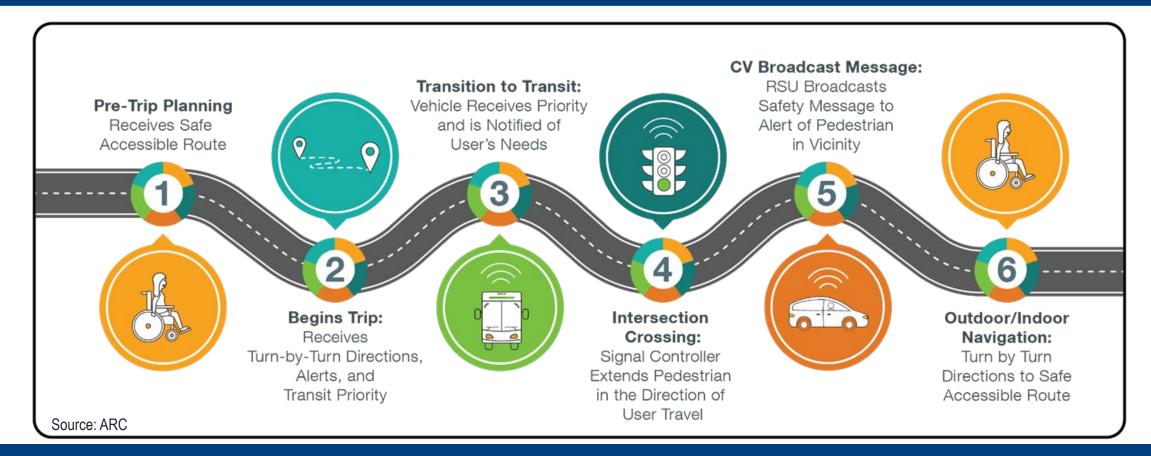
## ITS4US Study Area: Gwinnett County, GA

- Richly diverse area
- Major transit hubs
- 220 miles of sidewalk connect transit stops
- Includes Lawrenceville and suburban land use
- Wide and high-speed roadways
- Inconsistent pedestrian
  infrastructure





## Georgia Mobility and Accessibility Planner (G-MAP)





#### Navigation Provided by Mobility Mode Best Routes - Likely on Different Paths

#### **Eight Primary Categories**

- Person walking who has no mobility limitations
- Person walking who has minor mobility limitations
- Person walking with a mobility device (cane, walker, etc.) or pushing a stroller
- Person using a standard manual wheelchair
- Person using an electric wheelchair
- Person using a mobility scooter
- Person walking with some low vision limitations
- Person walking who is blind or has major vision limitations

U.S. Department of Transportation ITS Joint Program Office Link travel time impedance + event impedance (by mode)

#### **Event Impedance**

Link feature impedance Link is missing (width = 0) Link defect impedance Link completely blocked

Crossing link impedance Associated ramp is missing (width=0)

Impedance is so large that a wheelchair user needs to divert across the street at a prior road crossing





#### **Pedestrian Network Development Goals**

- G-MAP requires a navigable pedestrian network
  - Completely independent of the roadway network
  - Assign impedance to each pedestrian link for routing
  - Apply impedance at the logical link level, where pedestrians can change direction (network nodes)
- Previous GT networks were derived from parcel-level land use data and roadway centerlines
- OSM was selected for G-MAP pedestrian network preparation
  - OSM contains some sidewalks (about 30% in our study area)
  - OSM network structure is used in OTP-based routing apps

#### **Network Development Protocols**

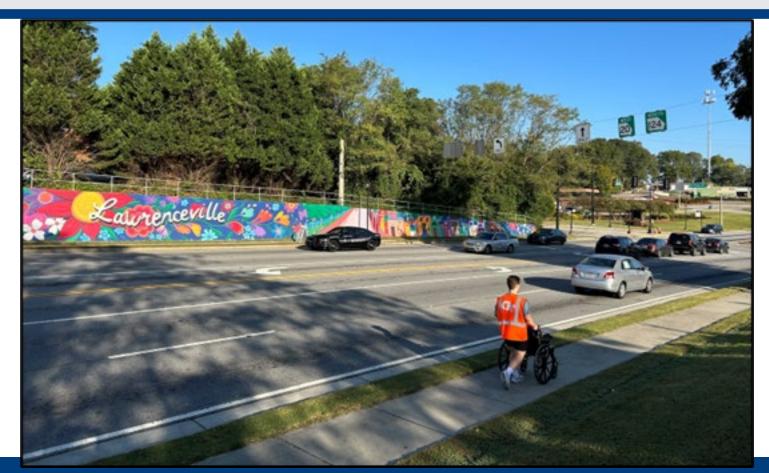
- Developed OSM network coding protocols
  - Disaggregate existing OSM pedestrian network
  - Add links to create a comprehensive, routable pedestrian network
- Path assessment
  - Identified private vs. public sidewalk
  - Removed potentially unsafe path links and dead-ends
- Identify final navigation network
  - Reconcile with AWS Neptune

#### Example of a Problem Crossing Added to the Demo Zone by the Public



 Unsafe 'Unmarked Crossing' link puts a wheelchair user into a high-speed right-turn intersection, with no protection barriers nor curb cuts to egress

#### **Pedestrian Infrastructure Data Collection**



- Vehicle-based video
  - Asset identification
  - Drive entire study area

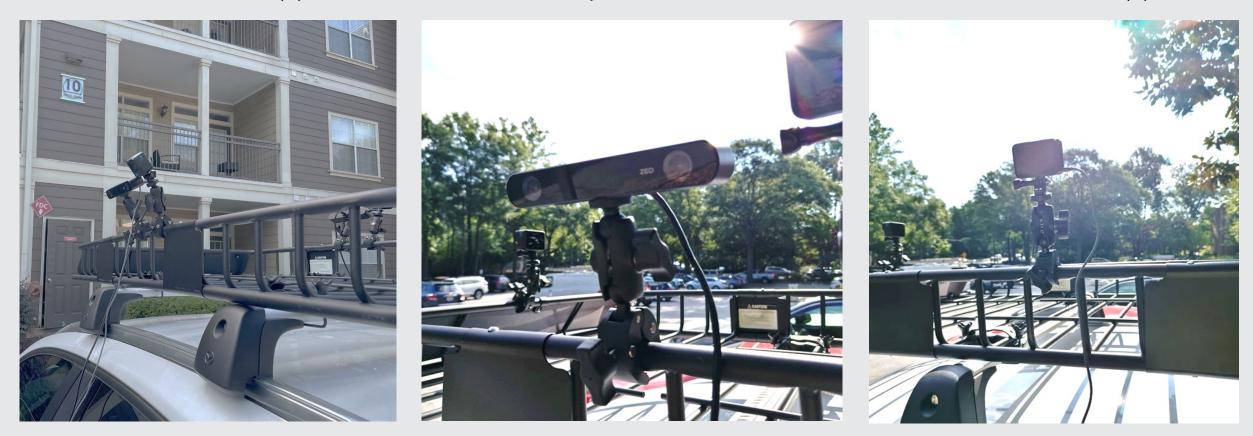
- Wheelchair-based video
  - Pedestrian assets manually inspected in the demo zone
  - 52 data collectors

#### **Vehicle Video Collection is Inexpensive**

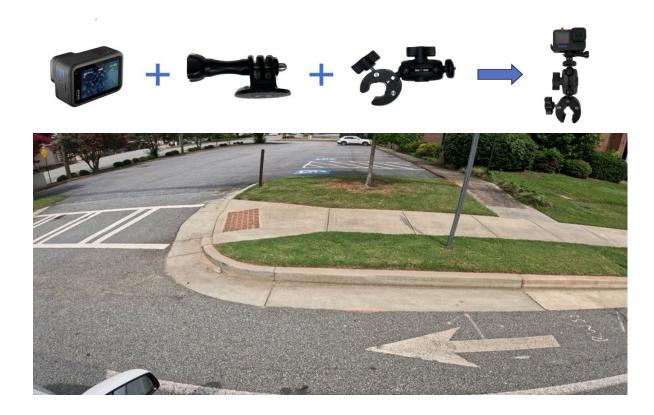
GoPro Cameras (3)

**Stereo-optical Camera** 

GoPro Cameras (3)



#### **Vehicle Flythrough Data Collection**



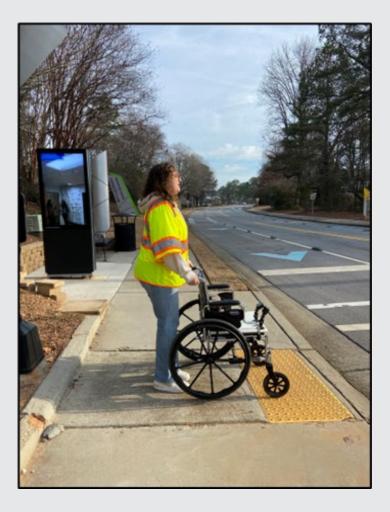
- GoPro camera passenger side video (plus driver side and front view)
- Manual flythrough for presence/absence
- Machine vision flythrough



### Wheelchair Video Data Collection Walking Speed (2-3 miles/hour)

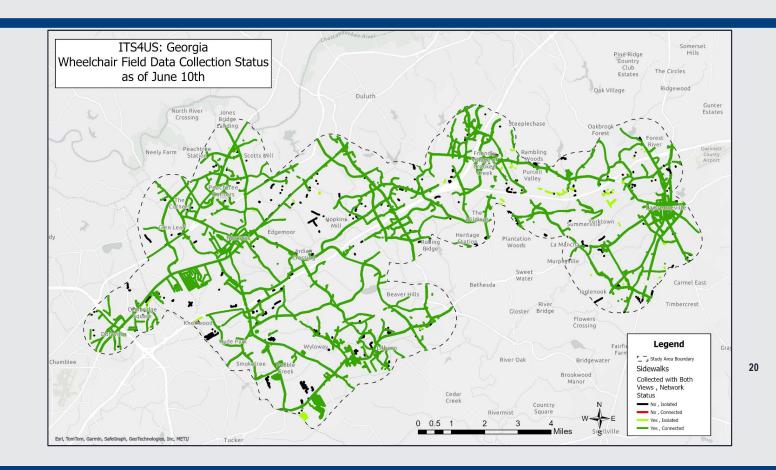


Forward-facing and down-angle cameras



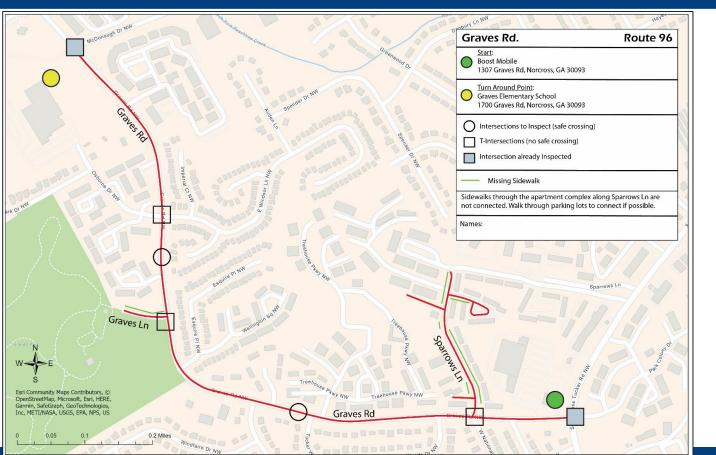
## **ITS4US Study Area**

- Study area
- 446 miles of sidewalks (10,896 sidewalk links)
- 3,148 road crossings (41 miles of crossings)
- 4,041 pedestrian ramps
- 17,235 vehicle curb cuts





#### **Wheelchair Video Archives**

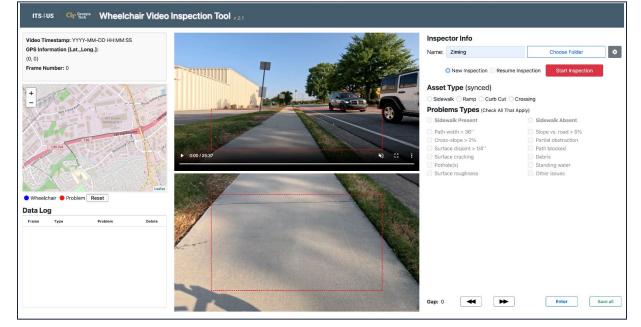


- Video provides an archive of asset design and condition
- Videos are used in online inspection procedures
- Engineers and planners can always refer back to the video to assess conditions



## Video Inspections for Asset Defects Sidewalks, Curb Ramps, Curb Cuts, Crosswalks

- Remote video inspection
  - Map location panel
  - Rolling video images
  - Inspection inputs
- Click image to stop video and record defect data
- Inspectors can identify 90% of design/ condition issues
  - Supporter changes in surface height >1/4", obstructions, width narrowing, debris, etc.



Supported browsers include  $Chrome^{\$},\,Edge^{\$},\,and\,Firefox^{\$}$ 



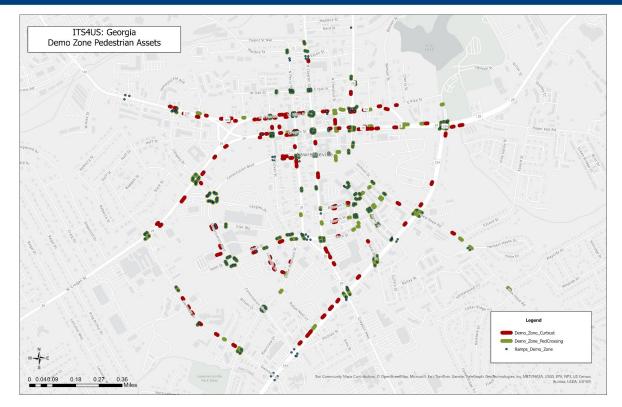
#### Wheelchair Camera Views Time-Aligned Video Inspection





- Forward view allows the user to identify features and condition
- Downward view supports assessment of surface condition

#### Asset Map for the Demo Zone



#### **Demo Zone Pedestrian Assets**



#### **Manual Field Inspections**

- Pedestrian assets inspected:
  - Sidewalks and pedestrian crossings
  - Pedestrian curb cuts (pedestrian ramps)
  - Vehicle curb cuts (driveway crossings)
- Intersection inspections (clockwise, typically four crossings)
  - Conducted in the City of Lawrenceville (demonstration zone)
  - Assess infrastructure vs. ADA design and condition
    - Signs, push buttons, signal heads, etc.
- Data are manually collected on an electronic inspection form
  - Tablet based data entry (phones also work)



# Tablet Excel Forms for Manual InspectionsCurb Ramps, Curb Cuts, Crossings

- Separate tablet data entry forms for:
  - Pedestrian road crossings
  - Pedestrian curb cuts (ramps)
  - Vehicle curb cuts (driveways)
- Each sheet contains relevant fields for each asset and sub-type
  - 10 curb ramp types
  - 4 vehicle curb cut types
- Manual data entry
  - Fresh forms for each route
  - Standardized naming conventions
- Uploaded to database after each trip



Time (24hr time)			L M								
D											
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et (perpendicular) Direction	Curb Cuts	Crossing Letter									
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Rath Cross Slope	time)										
an k Implemented	Crossing ID										
rolled Intersection of Curb Ramos	Latitude										
f Landing Pads	Longitude										
and Ramps	Zone	Ramps	Crossin	g Letter		_	_	_	_		_
urface Roughness Cracking Present	Nearest Street Address	Field	~ A-1	~ A-2		✓ B-2	~ C-1	~ C-2	~ <b>D-1</b>	~ D-2	~
Disjoints Present Present	Length on Street Side (ft)	time)									
t/Semi-Permanen	Length on Property Side (ft	Near/Far Node	Near	Far	Near	Far	Near	Far	Near	Far	
tions Present Isent	Walking Width (in)	Crossing ID									
Working p Condition	Walking Cross Slope	-									
ling Pad Condition Button Condition	Surface Roughness	Ramp ID	_							_	
ach Near Push	Right Flare Slope (from	Latitude									
em Landing Pad	street POV)	Longitude									
Crossing Signs Head Condition	Left Flare Slope (from	Zone									
Lamp Working Condition	street POV)	Cross Streets (list both)									
rg Pad Condition Autton Condition	Texture Pad	Nearest Street Address									
Button Height (in) sach Far Push	Texture Pad Condition	Ramp Direction									
em Landing Pad	Right Approach Ramp	Ramp Width (in)									
rossing Signs al Head Condition	Slope (from street POV)										
al Lamp Working al Lamp Visible	Cross Slope (from street	Passing Width (in)	_								
ting Pad	POV)	Ramp Slope									
	Left Approach Ramp Slope	Ramp Cross Slope									
	(from street POV)	Gutter Slope									
	Left Approach Ramp Cross	Right Flare Slope (from									
	Slope	property POV)									
	Field Notes	Left Flare Slope (from									
		property POV) (%)									
		Ramp Smoothness									
		Is ramp flush w/ street or									
		gutter? (<0.25in bump)									
		Detectable Warning									
		Surface Condition									
		Debris Present									
		Field Notes									

Step Controll Number of L Crossing Surface Crossing Surface Crossing Surface Pavement Sr P

## **Summary of ITS4US GDOT/ARC Outputs**

- Asset inventory (links, ramps, curb cuts, crossings, etc.)
- Pedestrian network for OTP navigation
  - Disaggregated OSM to logical links and completed network
  - Screened private and inaccessible links from navigation paths
- Inspected assets for design and condition (data structure)
- Assign time + event impedance to logical links
  - Crossing with no ramp is penalized for wheelchair mode
- Calculate and provides lowest impedance path via G-MAP for each mobility mode
- Everything is open architecture with open source software
  - Tech transfer documentation is forthcoming

# Anat Caspi, PhD

Director, Taskar Center for Accessible Technology Paul G. Allen School of Computer Science &

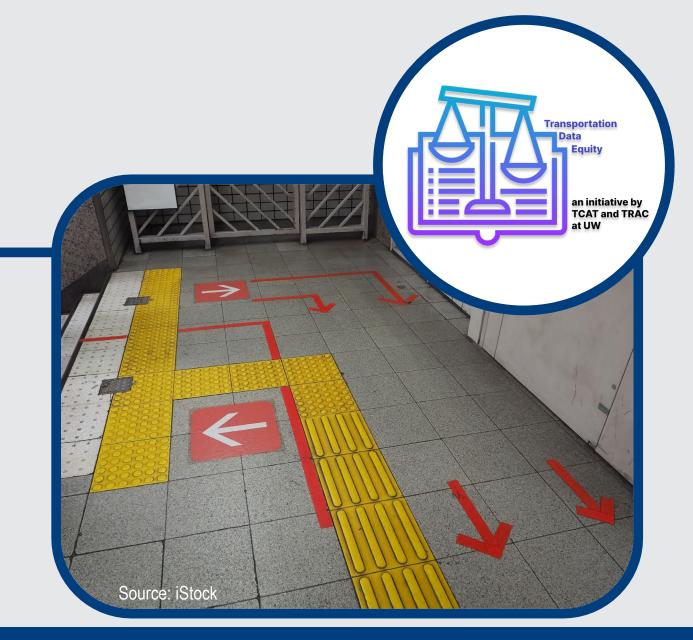
Engineering, University of Washington





## Transportation Data Equity Initiative

- King & Snohomish County, WA
- Multnomah & Colombia County, OR
- Harford & Baltimore County, MD
- Key Technologies:
  - Data Standards (OpenSidewalks, GTFS-Flex, GTFS-Pathways)
  - Open-Source Data Collection
  - Data Sharing System





<u>OpenSidewalks mapping with Oasis:</u> <u>Predicting Pedestrian Path Accessibility from</u> <u>Street-Level Video</u> (click link to access video)

# ordinale sharohil and use The left and over the friends

#### UW Taskar Center's: Applied AI methods for Accessibility-first Pedestrian Mapping

#### o <u>uwtcat@uw.edu</u>

JOIN US FOR OPEN THE PATHS-Our 8<sup>th</sup> annual conference on data-driven accessibilty-first transportation systems March 27-28, 2025 <u>TinyURL.com/TCATSignup</u>.

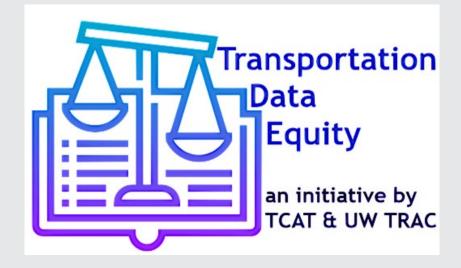


#### The Taskar Center for Accessible Technology



The Taskar Center for Accessible Technology (TCAT) at the Paul G. Allen School for Computer Science & Engineering develops translates and deploys technologies that increase independence and improve quality of life for People with Disabilities.

## Designing for the fullness of human experience

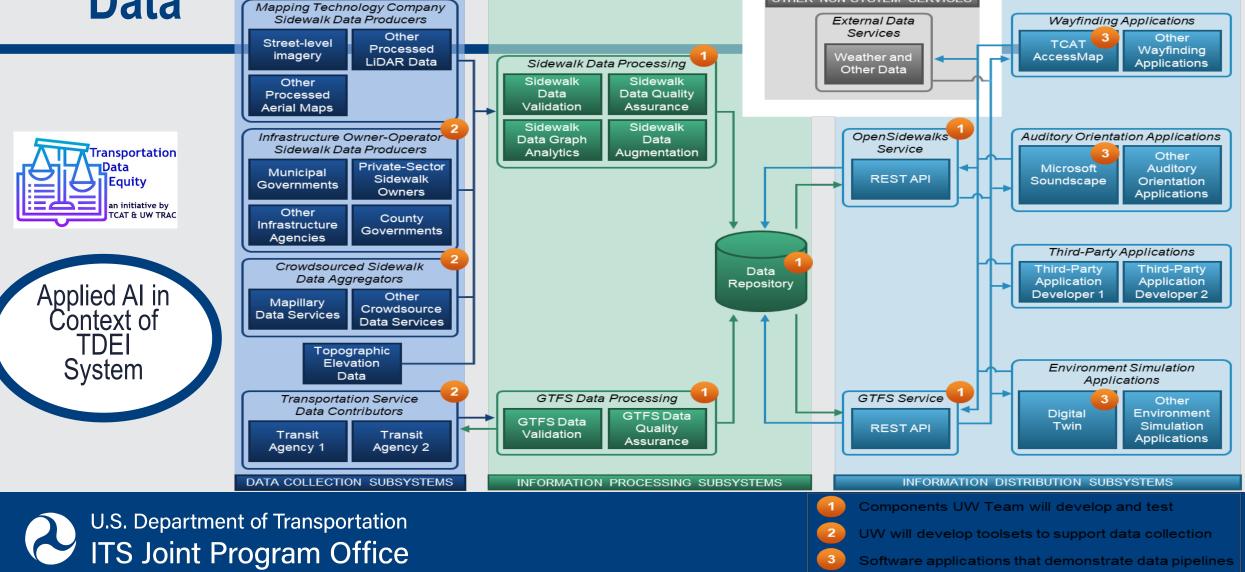




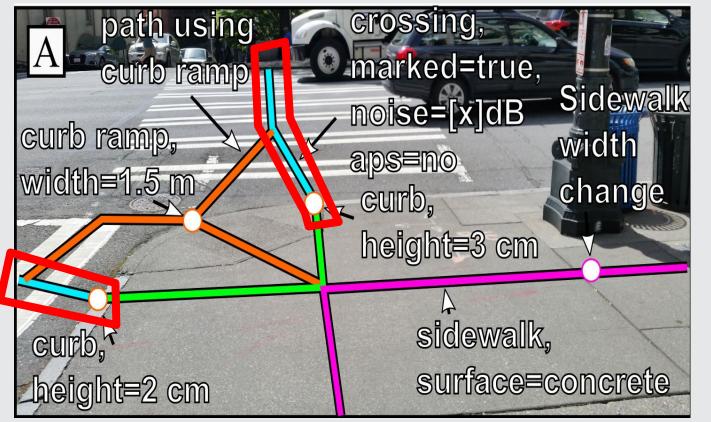
**IT'S TRANSPORTATION FOR ALL OF US** 



#### Applied Al for Accessibility-First Transportation Data



#### Accessibility-first Pedestrian Path Data: OpenSidewalks Data Schema



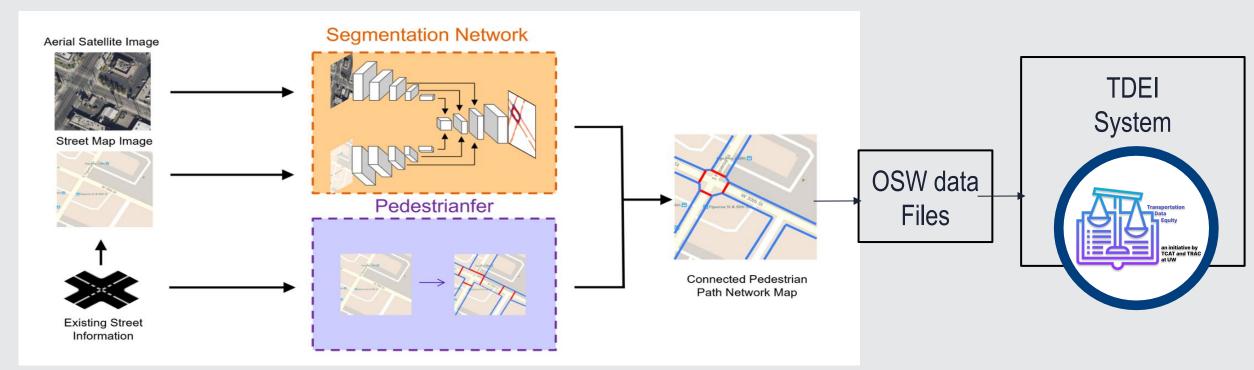
**OpenSidewalks.com** 

#### Github.com/OpenSidewalks/OpenSidewalk s-Schema: Repository for the draft proposal of the OpenSidewalks schema (github.com)

U.S. Department of Transportation ITS Joint Program Office

N. Bolten et al., "A pedestrian-centered data approach for equitable access to urban infrastructure environments," 2017 tinyurl.com/2017OpenSidewalks

#### **Prophet: An end-to-end system to infer a connected pedestrian path network**



#### Prophet- the Pedestrian Path Network Graph Inference Method outputs OpenSidewalks data at scale

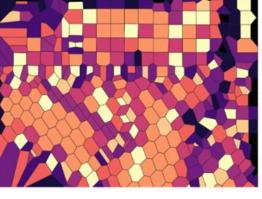
U.S. Department of Transportation ITS Joint Program Office Yuxiang Zhang, Bill Howe, Anat Caspi. "Reliable, Routable, and Reproducible: Collection of Pedestrian Pathways at Statewide Scale ". The 104th Transportation Research Board (TRB) Annual Meeting (2025). https://tinyurl.com/2024PathwayBench

#### **Prophet Compared to Satellite Imagery Segmentation Methods**

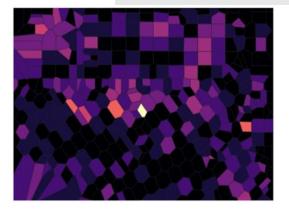
Method	Area	Global			Local		Local (relative to Ground Truth)		
Method	Area	# nodes	# edges	avg degree	avg CC	avg BC	edge-retrieval F1	TraversabilitySimilarity	
	Washington, D.C.	19245	21462	2.23	1.62	0.14	1.0	1.0	
Ground Truth	Portland, OR	937	1134	2.42	1.45	0.13	1.0	1.0	
	Seattle, WA	9386	10402	2.22	1.65	0.13	1.0	1.0	
	Washington, D.C.	27651	24948	1.80	6.44	0.02	0.84	0.37	
Pedestrianfer	Portland, OR	1615	1376	1.70	6.46	0.02	0.89	0.30	
	Seattle, WA	10002	8871	1.77	5.43	0.03	0.93	0.38	
	Washington, D.C.	48153	46369	1.93	5.77	0.03	0.84	0.35	
Tile2net	Portland, OR	937	844	1.80	2.77	0.04	0.76	0.04	
	Seattle, WA	12617	11732	1.86	5.01	0.03	0.90	0.17	
	Washington, D.C.	8908	10397	2.33	1.15	0.13	0.84	0.38	
Prophet(VGG-16)	Portland, OR	945	1056	2.23	1.39	0.13	0.90	0.47	
	Seattle, WA	5061	5497	2.17	1.37	0.13	0.89	0.41	
	Washington, D.C.	9967	11503	2.22	1.12	0.13	0.87	0.39	
Prophet (DeepLabv3)	Portland, OR	1138	1267	2.25	1.71	0.14	0.87	0.48	
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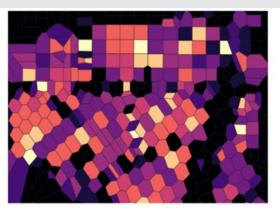
PathwayBench: Assessing Routability of Pedestrian Pathway Networks Inferred from Multi-City Imagery (arxiv.org)



(a) GT, *Traversability*=0.30



(b) Tile2Net, *Traversability=0.05* 

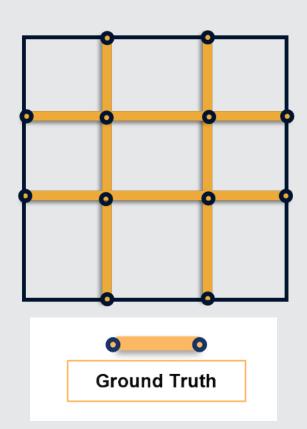


(c) Prophet, Traversability=0.15

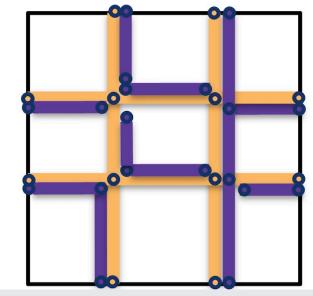


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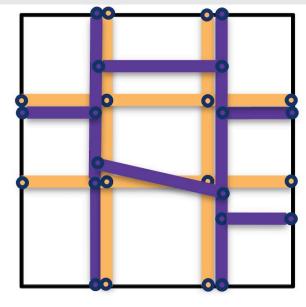
#### Traversability: Pedestrian Graph Evaluation must compare ROUTES not edges or nodes



Perfect precision and recall for *edges* Poor precision and recall of *routes* 



Poor precision and recall of *edges* Good precision and recall of *routes* 

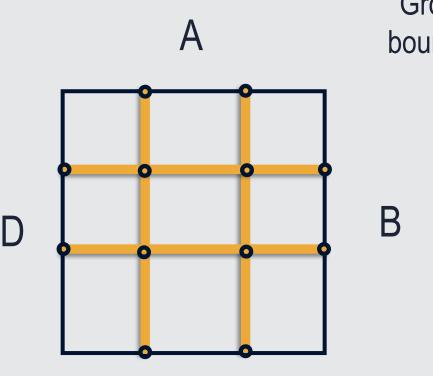


#### Typical metrics count edges and ignore connectivity



Yuxiang Zhang, Bill Howe, Anat Caspi. "Reliable, Routable, and Reproducible: Collection of Pedestrian Pathways at Statewide Scale ". The 104th Transportation Research Board (TRB) Annual Meeting (2025). https://tinyurl.com/2024PathwayBench

# Traversability: Intersection Traversability Is an Atomic Representation of Shift-invariant connectivity (1)



Ground truth boundary-toboundary traversable routes

 $A \leftrightarrow B$  $A \leftrightarrow C$  $A \leftrightarrow D$  $B \leftrightarrow C$  $B \leftrightarrow D$  $C \leftrightarrow D$ 

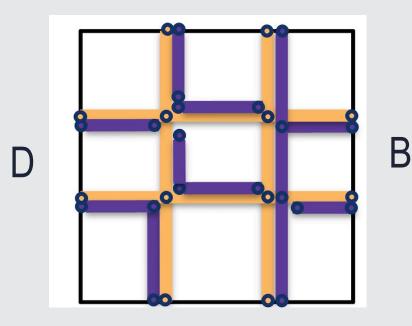
U.S. Department of Transportation A ITS Joint Program Office

С

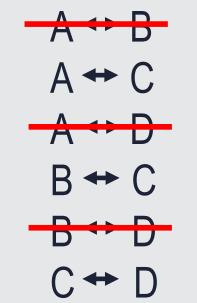
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# Traversability: Intersection Traversability Is an Atomic Representation of Shift-invariant connectivity (2)

Ground truth boundary-toboundary traversable routes



A



3/6 routes traversable

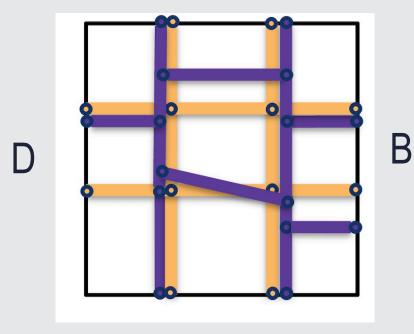
Perfect precision and recall of edges

U.S. Department of Transportation ITS Joint Program Office

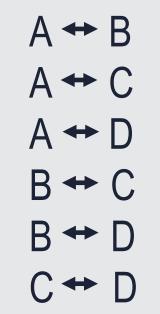
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# Traversability: Intersection Traversability Is an Atomic Representation of Shift-invariant connectivity (3)

Ground truth boundary-toboundary traversable routes



A



All 6/6 routes traversable

Some missing and misplaced edges

U.S. Department of Transportation ITS Joint Program Office

С

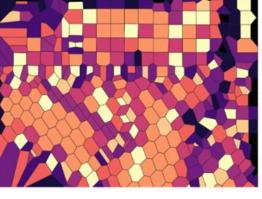
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## **Prophet Compared to Satellite Imagery Segmentation Methods**

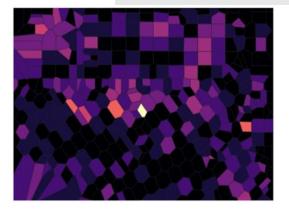
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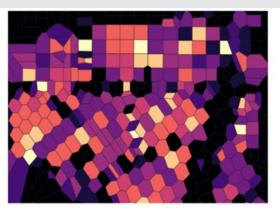
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(b) Tile2Net, *Traversability=0.05* 

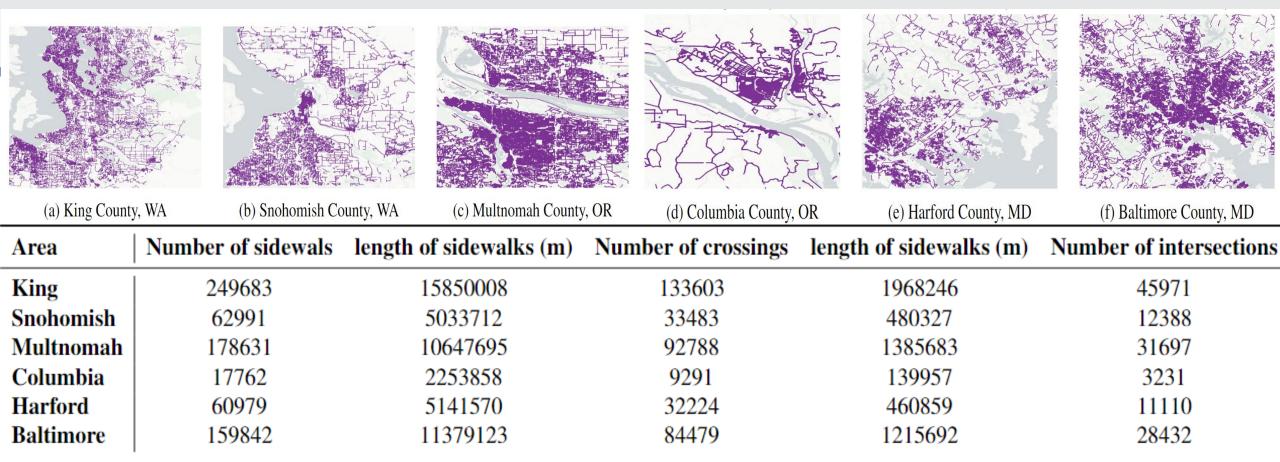


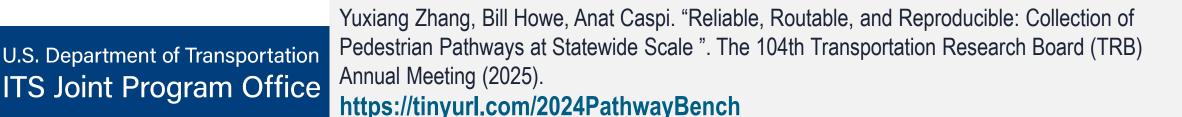
(c) Prophet, Traversability=0.15



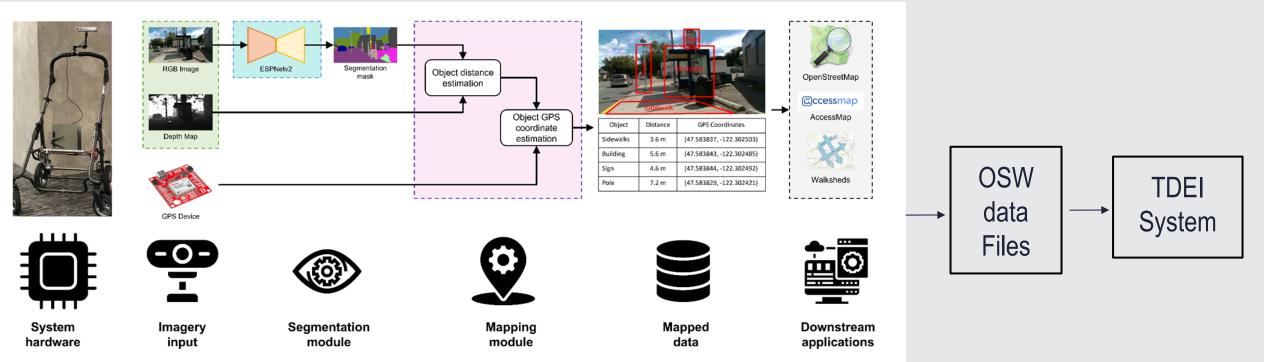
https://tinyurl.com/2024PathwayBench

## Prophet data: 4 U.S. Counties + 39 Counties in WA State





# OASIS: An on-device automated sidewalk mapping and assessment system





Yuxiang Zhang, Suresh Devalapalli, Sachin Mehta, Anat Caspi. "OASIS: Automated Assessment of Urban Pedestrian Paths at Scale". The 103rd Transportation Research Board (TRB) Annual Meeting (2024)

Tinyurl.com/2023OasisSystem

## **Oasis Pilot Study: North Seattle and Bellevue Schools**



- OASIS mapped an area in north Seattle, in collaboration with King County Metro, and 5 school ¼ mi walksheds in Bellevue, WA
- ♦ OASIS reduced operator time by over 80%
- OASIS Generated mapping data with comparable accuracy to manual on-the-ground vetters
- OASIS Generated mapping data per OpenSidewalks data schema

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Yuxiang Zhang, Suresh Devalapalli, Sachin Mehta, Anat Caspi. "OASIS: Automated Assessment of Urban Pedestrian Paths at Scale". The 103rd Transportation Research Board (TRB) Annual Meeting (2024) **Tinyurl.com/2023OasisSystem** 

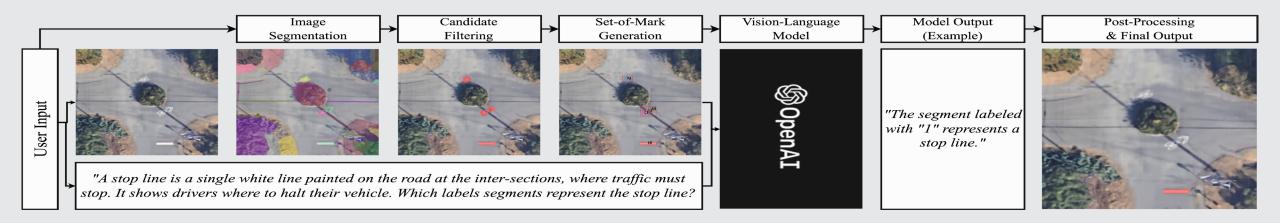
# Towards Zero-Shot Annotation of the Built Environment with Vision-Language Models



Procedure using VLM to annotate diverse urban features from satellite images at scale, reducing the dependency on human effort

### Remove dependency on costly annotations

- Scale to hundreds of diverse regional features (where no annotations, regardless of cost, could go
- Leverage imagery that has already been acquired and processed





Han, B., Yang, Y., Caspi, A., & Howe, B. (2024). Towards Zero-Shot Annotation of the Built Environment with Vision-Language Models (Vision Paper). *arXiv preprint arXiv:2408.00932*. (accepted

to SigSpatial, 2024; in proceedings) Tinyurl.com/2024VLMSidewalks

# **VLM Procedure On our Imagery**

### Results

Feature	DP	SoM (NC)	SoM (IC)	SoM (Comb)	
Stop Line 0.0000		0.2483	0.3354	0.3657	
Raised Table	0.0190	0.3315	0.4069	0.4189	

#### Quantitative:

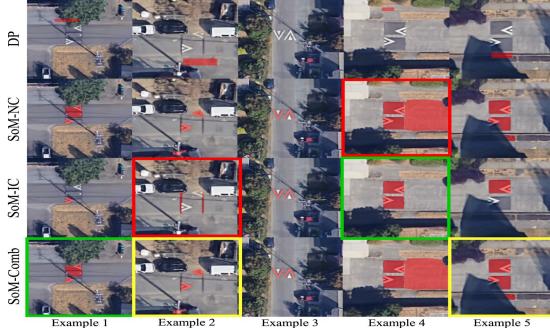
- Baseline (direct prompting VLM) failed, achieving essentially zero overlap with ground truth.
- Our procedure significantly improves performance, achieving 24%~40% IoU depending on the variant.

Qualitative:

• This procedure guaranteed to identify features partially (always) or Fully (occasionally). Future study to understand feasibility for other features.

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### **Examples**



Han, B., Yang, Y., Caspi, A., & Howe, B. (2024). Towards Zero-Shot Annotation of the Built Environment with Vision-Language Models (Vision Paper). *arXiv preprint arXiv:2408.00932*. (accepted

to SigSpatial, 2024; in proceedings) Tinyurl.com/2024VLMSidewalks

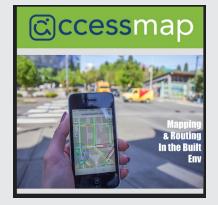
# **Deployed Capacity Building Tools**



## OpenSidewalks

Pedestrian-centered approach, data specification and tools to share accessibility information about urban street environments

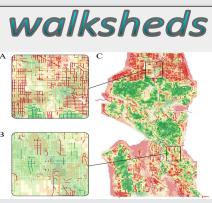
https://sidewalks.washington.edu/



Accessmap.appautomated custom routing for personal mobility profiles



https://transitequity.cs.washington.edu/ TDEI: data sharing Ecosystem for accessibility-first Transportation data



https://walkshed.sidewalks.washi ngton.edu/ Walkshods

Walksheds- Urban analytic dashboards for equitable urban planning



https://tinyurl.com/SidewalkScore21

# Applied AI for OpenSidewalks collection: Summary

- Pedestrian network data is essential to a transportation network.
- The data is hard to collect and maintain manually.
- The UW team presented several AI-based methods to automate sidewalk data collection and mapping, at various scales and with heterogeneous inputs
- The systems provide sidewalk data (in standardized OpenSidewalks format) that will benefit various stakeholders.
- The systems use off-the-shelf components and are easy to replicate and deploy for a larger scale use.
- The systems can also be incorporated into smart city technology and sensor network plans to automate regular city audits and data collections

## Any Questions? Anat Caspi & Ricky Zhang

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uwtcat@uw.edu





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# **ITS4US Contact Information**

#### GDOT

https://georgia-map.com/ Alan Davis Co-Project Management Lead aladavis@dot.ga.gov

Kofi Wakhisi Co-Project Management Lead <u>kwakhisi@atlantaregional.org</u>

#### HIRTA

https://transithealthconnector.org/ Brooke Ramsey Project Management Lead BRamsey@ridehirta.com

## NFTA

https://bnmc.org/allaccess Robert Jones Concept Deployment Lead robert.jones@nfta.com

Kelly Dixon Project Management Lead kdixon@gbnrtc.org

University of Washington https://transitequity.cs.washington.edu/ Anat Caspi Deployment Development Lead caspian@cs.washington.edu

### **ITS4US** Program

Elina Zlotchenko Program Manager, ITS4US USDOT ITS JPO Elina.Zlotchenko@dot.gov

**ITS4US Deployment Program Video** 

https://youtu.be/pztl1IRyXAc



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